The Vector Equation of a Line in for AI HL

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Vector Form of the equation of a Line

 $\vec{r} = \vec{a} + \lambda \vec{b}$

or $\begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} x_0 \\ y_0 \\ z_0 \end{pmatrix} + \lambda \begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix},$

where \vec{a} is the position vector giving the position of a point on the line at $\lambda = 0$, \vec{b} is a vector <u>parallel</u> to the line (the direction vector of the line) and parameter λ is a variable. (x₀, y₀, z₀) is a point on the line.

Two lines are parallel if their direction vectors are scalar multiples of each other. In other words $\vec{r_1} = \vec{p_1} + \lambda \vec{d_1}$ and $\vec{r_2} = \vec{p_2} + \mu \vec{d_2}$ are parallel, if $\vec{d_1} = k \vec{d_2}$ for some scalar k.

Example

 $\vec{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 4 \\ 6 \\ 1 \end{pmatrix}$

Parametric Form of the equation of a Line

 $\begin{aligned} \mathbf{x}(\lambda) &= \mathbf{x}_0 + \mathbf{x}_1 \, \lambda \\ \mathbf{y}(\lambda) &= \mathbf{y}_0 + \mathbf{y}_1 \, \lambda \\ \mathbf{z}(\lambda) &= \mathbf{z}_0 + \mathbf{z}_1 \, \lambda \end{aligned}$ Where parameter λ is a variable and \mathbf{x}_0 , \mathbf{y}_0 , \mathbf{z}_0 , \mathbf{x}_1 , \mathbf{y}_1 and \mathbf{z}_1 are scalar constants. (\mathbf{x}_0 , \mathbf{y}_0 , \mathbf{z}_0) is a point on the line. $\begin{pmatrix} x_1 \\ y_1 \\ z_1 \end{pmatrix}$ is the direction vector of the line.

Example

$$\begin{split} x(t) &= 3 + 4\lambda \\ y(t) &= 5 + 6\lambda \\ z(t) &= -2 + \lambda \end{split}$$

Converting Between the Forms

This is easy since it just requires adding or removing vector brackets.

Example: Convert

 $x = 4\lambda + 3,$ $y = 6\lambda + 5,$ $z = \lambda - 2$ to parametric vector form. $\begin{pmatrix} x \\ x \end{pmatrix} \begin{pmatrix} 3 \\ y \end{pmatrix} \begin{pmatrix} 4 \end{pmatrix}$

$$\vec{r} = \begin{pmatrix} x \\ y \\ z \end{pmatrix} = \begin{pmatrix} 3 \\ 5 \\ -2 \end{pmatrix} + \lambda \begin{pmatrix} 4 \\ 6 \\ 1 \end{pmatrix}$$