# The Vector Forms of Planes

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Cartesian Form of the equation of a Plane	Vector Form of the equation of a Plane
ax + by + cz = D, where a, b, c and D are scalars.	$\vec{r} = \vec{a} + \lambda \vec{b} + \mu \vec{c}$ or
<b>Example:</b> $3x + 5y - 2z = 5$ Normal Vector Form of the equation of a Plane	$\vec{r} = \begin{pmatrix} x_0 \\ y_0 \end{pmatrix} + \lambda \begin{pmatrix} x_1 \\ y_1 \end{pmatrix} + \mu \begin{pmatrix} x_2 \\ y_2 \end{pmatrix}$ , where $\vec{a}$ is a position vector
$\begin{pmatrix} x \end{pmatrix}$	$\begin{pmatrix} z_0 \end{pmatrix} \begin{pmatrix} z_1 \end{pmatrix} \begin{pmatrix} z_2 \end{pmatrix}$
$\vec{r} \cdot \vec{n} = D$ , where $\vec{r} = \begin{bmatrix} y \\ z \end{bmatrix}$ , is the position vector, $\vec{n}$ is a vector <u>perpendicular</u> to the plane and D is a scalar. <b>Example:</b> $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \begin{pmatrix} 3 \\ 5 \\ -2 \end{pmatrix} = 5$ .	giving the position of a point on the plane at $\lambda = \mu = 0$ , $\vec{b}$ and $\vec{c}$ are non-parallel vectors in the plane and parameters $\lambda$ and $\mu$ are variables. <b>Example:</b> $\vec{r} = \begin{pmatrix} 2\\1\\3 \end{pmatrix} + \lambda \begin{pmatrix} 0\\1\\0 \end{pmatrix} + \mu \begin{pmatrix} 1\\-1\\-1 \end{pmatrix}$
<b>Converting between the Forms</b>	

Normal Vector Form to Cartesian Form and vice versa Evaluation of the dot product of the vector form immediately gives the Cartesian form.

(x)**Example** Convert  $\begin{bmatrix} y \\ z \end{bmatrix} \cdot \begin{bmatrix} 5 \\ -2 \end{bmatrix} = 5$  to Cartesian form.

Doting gives 3x + 5y - 2z = 5.

"Undoting" the Cartesian form immediately gives the vector form.

#### **Cartesian Form to Vector Form**

Use the Cartesian form to find three points A, B & C on the plane. Use  $\vec{a} = \overrightarrow{OA}$ ,  $\vec{b} = \overrightarrow{AB}$  and  $\vec{c} = \overrightarrow{BC}$  or whichever are convenient.

**Example** Convert 3x + 5y - 2z = 5 to parametric vector 

A is (2, 1, 3), B is (0, 1, 0), C is (1, 0, -1).  

$$\vec{a} = \vec{OA} = \begin{pmatrix} 2\\1\\3 \end{pmatrix}, \vec{b} = \vec{BA} = \begin{pmatrix} 2\\0\\3 \end{pmatrix}, \vec{c} = \vec{BC} = \begin{pmatrix} 1\\-1\\-1 \end{pmatrix}$$
, so:  
 $\vec{r} = \begin{pmatrix} 2\\1\\3 \end{pmatrix} + \lambda \begin{pmatrix} 2\\0\\3 \end{pmatrix} + \mu \begin{pmatrix} 1\\-1\\-1 \end{pmatrix}$ 

Vector Form to Normal Vector Form We need a vector  $\vec{n}$  perpendicular to the plane, so use

 $\vec{n} = \vec{b} \times \vec{c}$ . Then we use  $\vec{a}$  to find D.

**Example** Convert  $\vec{r} = \begin{pmatrix} 2 \\ 1 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 2 \\ 0 \\ 3 \end{pmatrix} + \mu \begin{pmatrix} 1 \\ -1 \\ -1 \end{pmatrix}$  to vector

form.

$$\vec{n} = \vec{b} \times \vec{c} = \begin{pmatrix} 3\\5\\-2 \end{pmatrix}.$$

$$\begin{pmatrix} 2\\1\\3 \end{pmatrix} \cdot \begin{pmatrix} 3\\5\\-2 \end{pmatrix} = 5, \text{ so our equation is } \vec{r} \cdot \begin{pmatrix} 3\\5\\-2 \end{pmatrix} = 5.$$

#### Vector Form to Cartesian Form

Convert to vector form as above and then dot it into Cartesian form.

**Example** Convert 
$$\vec{r} = \begin{pmatrix} 2\\1\\3 \end{pmatrix} + \lambda \begin{pmatrix} 2\\0\\3 \end{pmatrix} + \mu \begin{pmatrix} 1\\-1\\-1 \end{pmatrix}$$
 to Cartesian

form.

From the above example we know the equation is

 $\vec{r} \cdot \begin{vmatrix} 5 \\ 5 \\ -2 \end{vmatrix} = 5$ , which dots into 3x + 5y - 2z = 5.

# **Planes with Vectors Problems vs. Planes with Matrices Problems**

We use both matrices and vectors to solve problems with planes. However, the types of problems solvable with matrices and vectors are different.

Planes with vectors problems tend to be finding the equation of one plane perpendicular to a given vector or parallel to two vectors and passing through a given point.

Planes with matrices problems tend to be about three planes and finding the values of one or two unknown coefficients such that the planes intersect in a point, line, or not at all.

## Given three points in a plane, construct the 3 equations

Call the points A, B, & C Create 2 vectors from the 3 points, for example **AB** & **AC**.

#### To create the Normal Vector Form of the Equation of a Plane

 $n = AB \times AC$ 

Use any point, say A, to find d.  $d = OA \bullet n$ 

The normal vector equation is  $\mathbf{r} \bullet \mathbf{n} = \mathbf{d}$ 

#### Example

A (1, 2, 3), B (2, -1, 4), C (-2, 1, 3)  

$$\overrightarrow{AB} = \begin{pmatrix} 1 \\ -3 \\ 1 \end{pmatrix}, \overrightarrow{AC} = \begin{pmatrix} -3 \\ -1 \\ 0 \end{pmatrix}$$
  
 $\vec{n} = \overrightarrow{AB} \times \overrightarrow{AC} = \begin{pmatrix} 1 \\ -3 \\ 1 \end{pmatrix} \times \begin{pmatrix} -3 \\ -1 \\ 0 \end{pmatrix} = \begin{pmatrix} 1 \\ -3 \\ -10 \end{pmatrix}$   
 $d = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} \bullet \begin{pmatrix} 1 \\ -3 \\ -10 \end{pmatrix} = 1 - 6 - 30 = -35$   
So our equation is  $\vec{r} \bullet \begin{pmatrix} 1 \\ -3 \\ -10 \end{pmatrix} = -35$ 

## To create the Cartesian Form of the Equation of a Plane

Dot out the normal vector equation.

#### Example

 $\begin{pmatrix} x \\ y \\ z \end{pmatrix} \bullet \begin{pmatrix} 1 \\ -3 \\ -10 \end{pmatrix} = -35$ So our equation is x - 3y - 10z = -35

## To create the Vector Form of the Equation of a Plane

Again use  $\overrightarrow{AB}$ ,  $\overrightarrow{AC}$  and  $\overrightarrow{OA}$ 

The vector equation is  $\vec{r} = \overrightarrow{OA} + \lambda \overrightarrow{AB} + \mu \overrightarrow{AC}$ 

#### Example

So our equation is 
$$\vec{r} = \begin{pmatrix} 1 \\ 2 \\ 3 \end{pmatrix} + \lambda \begin{pmatrix} 1 \\ -3 \\ 1 \end{pmatrix} + \mu \begin{pmatrix} -3 \\ -1 \\ 0 \end{pmatrix}$$